

# A Digital Twinning Approach to Decarbonisation: Research Challenges

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## INTRODUCTION

Transportation accounts for around 27% of green house gas emissions in the UK [7]. While an obvious priority area for decarbonisation, and aligned to the UK government goal of reducing emissions by 68% for 2030, the free-market nature of the transportation sector combined with its fundamentally implicit and pervasive connections to all aspects of society and national infrastructure mean that all decarbonisation efforts to date have been siloed within a single transport sector [18], e.g. only considering greener aviation fuels. Truly decarbonising transport requires radical changes to the entire transport infrastructure, and since that transport does not happen in isolation, a single user often using multiple modes, we need a view over the whole transport system.

The first step to solving a problem is to understand it. As a result of the fragmented nature of the transportation sector, there is currently no system level view. Without the ability to monitor even adjacent transport domains, the ability for people or organisations to (dynamically) adapt their operations for decarbonisation outcomes is unrealistic. As transportation is a complex social-techno-economic system, information and knowledge sharing is a *must* to be able to understand and explore potential solutions to the decarbonisation challenge.

We believe a **Federated Digital Twinning Approach** has the potential to tackle transport decarbonisation problems, and, in this extended abstract, **we give an overview of the research required to tackle the fundamental challenges around digital twin design, generation, validation and verification.**

## FEDERATED DIGITAL TWINNING FOR DECARBONISATION

Digital Twins [15] (DTs) are data-driven virtual representations of physical (or conceptual) assets. By applying transportation data to DTs, they can provide a pathway to understanding the current transport system, and enable experimentation with future transport systems: a necessary ability for decarbonisation (or any optimisation) given that physical experimentation at scale is not feasible or timely.

DTs may take many forms: from simple displays of data (dashboards), machine learning-based data labelling (convolutional neural networks), large-scale simulations (discrete event simulators), numerical models based on partial differential equations (weather prediction), 3D models, and logical models building on discrete mathematical representations of entities and their interactions. While many useful mode-specific closed-loop DTs exist within transport, e.g. Port of Dover Twin [14] and elsewhere [1], they remain siloed, lacking interoperability or a standardised framework

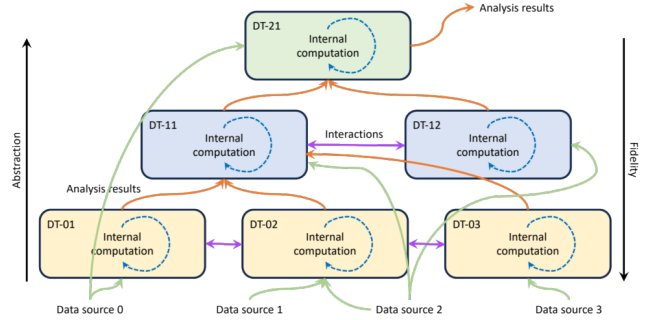


Figure 1: Federated Digital Twinning Approach

for communication. For example, the port only considers port operations, excluding freight shipping entering and road congestion leaving the port. To overcome the lack of information sharing in the transport sector we propose *federated digital twinning approach for transport decarbonisation* as shown in Fig. 1.

Federated twins compose multiple DTs together to give better operational oversight. This is a step change from classic digital twins that only have interoperability between the physical system and a single twin. Moving to a federated twinning approaches raises many interesting research challenges.

## FEDERATED DIGITAL TWINNING RESEARCH CHALLENGES

We seek to derive value from the federation of multiple twins, possibly owned by different stakeholders, e.g. utilising power generation models alongside traffic and road models to develop effective decarbonisation policies. Fundamentally, integrating Digital Twins means we need **approaches to combine their underlying models** and to be sure these combinations make logical sense. This is a challenge: these models are heterogeneous and we need a well-defined and common theory to be able to use them together. While domain-specific modelling tools have been extensively developed over the years [4, 12, 17], the techniques for combining models are under-explored but essential.

This combined modelling approach is further complicated by: 1. **multi-scale modelling**—one twin might be for a single component, e.g. a car, while another may be at a completely different level of abstraction or fidelity, e.g. city-scale; 2. **multi-temporal modelling**—models work at different time scales and some modelling techniques will trade granularity for performance, e.g. it is quicker to make a weather prediction based on seasons than a full atmospheric weather simulation; 3. **integration of multiple model**

117 **types**, e.g. discrete models of software behaviours, continuous mod- 175  
 118 els of physical behaviours, and probabilistic models of environment, 176  
 119 devices failure rates, and data accuracy; and 4. **dynamic models**— 177  
 120 the systems we model are subject to change, e.g. deployment of 178  
 121 more 5G/6G cells, new road infrastructure being built, emergent be- 179  
 122 haviour of crowds, and these need to be integrated into the models. 180  
 123 Throughout all these challenges there is a need for rigour: transport 181  
 124 systems are critical infrastructure, have dramatic effects on peoples’ 182  
 125 lives, and we do not have time to take multiple-shots at getting the 183  
 126 decarbonisation right. 184

## 127 Proposed Approach 185

129 **We propose to develop new theories and tools to reason about 186**  
 130 **federated DT models based on Formal Methods**—mathematical 187  
 131 descriptions of systems that allow for strong reasoning, e.g. creating 188  
 132 proofs of correctness via mathematical logic. Importantly, the model 189  
 133 specification will be driven by the incoming data<sup>1</sup>, but not fully 190  
 134 defined by it. In this way we maintain control of core reasoning 191  
 135 aspects, i.e. badly inferred models can be disregarded (possibly by 192  
 136 a human-in-the-loop). Newer formal modelling approaches allow 193  
 137 for describing the probabilistic scenarios that are essential when 194  
 138 working with real data that sometimes goes missing, is incorrect or 195  
 139 non-trustworthy; and for describing the spatial elements of systems, 196  
 140 which is crucial when working with transport and other physical 197  
 141 systems. 198

142 Formal theories will be applied when reasoning about systems 199  
 143 themselves, and, at a meta-level to reason about the integration of 200  
 144 Digital Twins. For example, we may model dataflow between twins 201  
 145 to detect possible attack vectors such as a malicious twin using 202  
 146 electric vehicle power data to detect areas of stress on the power 203  
 147 grid and other critical infrastructure. 204

148 Bigraphs [13, 16] may form the common (formal) meta-model 205  
 149 for describing federated Digital Twins. Bigraphs model systems 206  
 150 with strong notions of spatial locality, e.g. a car within a particular 207  
 151 charging station, and non-local connectivity, e.g. modelling the 208  
 152 communication between smart traffic lights and a central control 209  
 153 room. A key benefit of bigraphs is the visual modelling format—not 210  
 154 too unlike what you might draw on a whiteboard—making them 211  
 155 accessible to a wide range of transport experts without needing 212  
 156 detailed formal modelling knowledge. 213

157 For analysis, bigraphs explicitly represent **all** possible temporal 214  
 158 evolutions of a system as opposed to simulation which only consid- 215  
 159 ers a set of traces. Bigraphs support underlying stochastic process 216  
 160 (e.g. Markov Chains and Markov Decision Processes) describing 217  
 161 the evolution of a system in terms of probabilities or rates, giving 218  
 162 access to automated verification with tools like PRISM [10] to an- 219  
 163 swer queries such as “given a battery error of 5% the probability of 220  
 164 running out of charge before reaching a charger is less than 0.001”. 221

165 A single model will not be enough for all situations, and there 222  
 166 are interesting questions around whether we want models to prove 223  
 167 slow, but accurate, or fast, with wider confidence interval results. 224  
 168 Partially Observable Markov Decision Processes (POMDPs) will be 225  
 169 well-suited for our requirements as they encompass uncertainty on 226  
 170 the state observation. However, the theory of bigraphs will require 227  
 171 extensions as it does not yet support POMDPs. Another important 228  
 172 229

173 <sup>1</sup>Which is a defining feature of digital twins versus traditional modelling approaches. 230  
 174 231

feature of POMDPs is that they support the synthesis of policies (i.e. 175  
 sequences of actions), that allow the models to perform optimisation 176  
 (which can be with respect to metrics like decarbonisation). We 177  
 also focus on how to parametrise Digital Twins models by the data 178  
 stream generated and transmitted by the physical system, i.e. we 179  
 need live models@runtime [2]. We expect out-of-order messages 180  
 and mislabelling to be potential issues, but these fit those as another 181  
 form of uncertainty in the model. 182

When designing and managing large-scale systems involving 183  
 multiple agents and stakeholders it is challenging to reason about 184  
 (future) properties of the overall system e.g. CO<sub>2</sub> emissions over 185  
 time. We will express these kinds of properties using rewards in 186  
 Continuous Stochastic Logic (PCTL) [8], and we will verify them 187  
 through model checking using PRISM. An additional challenge 188  
 is enabling non-expert users to express these properties, and we 189  
 believe approaches like FRET [6] and n2spec [5] to be of use here. 190

We will develop extensions of the standard verification algo- 191  
 rithms to support checking a set of properties across a hierarchy 192  
 of Digital Twins and not just over one. For models with large state 193  
 spaces, exhaustive model checking can be computationally expen- 194  
 sive, so we will utilise the built-in discrete-event simulator in PRISM 195  
 to apply statistical model checking (SMC) [19] and compute ap- 196  
 proximately correct results. SMC effectively samples the model 197  
 space through repeated simulation instead of exhaustive search 198  
 resulting in higher performance at a cost of accuracy. Building on 199  
 recent advances in the field [3, 9, 11], we will define more refined 200  
 properties using spatial logics. 201

Open questions remain around how the end-users will specify 202  
 the models: while the visual approach of bigraphs can be exploited, 203  
 it is possible we require additional programming language sup- 204  
 port: what does a programming language specifically for digital 205  
 twin models look like? A complementary approach is mechanically 206  
 generating suitable models of each component of the system via 207  
 process mining. This requires discretisation and different levels of 208  
 abstraction and formulate precise relations between models to form 209  
 an overall coherent hierarchy. Once we have the model running, 210  
 how best to express the structure of the system to the user? We sug- 211  
 gest a control interface updated with the results of model checking 212  
 as the become available. 213

## 214 CONCLUSION 215

A federated digital twinning approach has the potential to give 216  
 the whole-system view required for timely and radical transport 217  
 decarbonisation and missing in current approaches. 218

To fully utilise federated twins we must overcome challenges 219  
 related to model combination across scales, fidelity, and modelling 220  
 types. We believe formal methods is a core component to solving 221  
 this challenges. If we get it right, it provides the underlying trust 222  
 we need for federated twins of such critical importance. 223  
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